

Lifting Modules Shop-Floor

Max. lifting force 1,000 to 6,000 N, stroke from 200 to 600 mm, manual-hydraulic and electro-mechanical version



Lifting module for workshop and assembly

Application

Principal use

Service

transfer

applications in the industry.

places in workshops

Assembly fixtures

mid-sized objects

Fixing and installation

Industrial assembly working places

Height adjustment of assembly working

Adjusting systems in supply processes of

· Handling systems for product packing and

ponents of the user at the top plate, the lifting

For fixing of modulub modules at the bottom plate, the lifting module has an interface 200 x 200. This plate can also be used to fix the lifting module on a flat level floor. For fixing, 4 screws M10 of property class 10.9 as well as

For increased stability, a base plate, which can be mounted to the bottom plate, is available as accessory. Fixing on the floor is made by

module has an interface 140 x 140.

heavy-duty plugs are to be used.

means of the base plate.

Advantages Simple and intuitive operation

- Working in ergonomically opt
- Sturdy industrial design
- Increase of quality in manufaction and assembly processes
- Increase of assembly through and productivity
- High level of safety against st overloads

rsion	
n timum height	moduhub Lifting module
cturing	Part no. 8915-0X-X0-X
nput tatic	Technical dataMax. lifting force:1,000 to 6,000 NMax. bending moment:500 NmStroke:200 to 600 mm
	Operation • Foot pedal • Foot switch • Hand panel Image: Second pedal Image: Second pedal Image: Second pedal
r is particularly g assembly fix- demonstration ons as well as ents in medical used as a base ng and lowering it only.	 Combinable with the modules Rotating modules – horizontal axis DMH 200 as per data sheet M 1.101 DMHe 200 as per data sheet M 1.201 Tilting modules KMB 100 as per data sheet M 2.101 KME 100 as per data sheet M 2.201 Rotating modules – vertical axis DMV 600 as per data sheet M 1.301 DMVe 600 as per data sheet M 1.201 Cart modules WMS as per data sheet M 5.101 Floor modules as per data sheet M 6.101
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- al operating elements, lines and connectors as per data sheet M 8.203
- Base and adaptor plates as per data sheet M 8.100 and M 8.110 • Table plates
- as per data sheet M 8.130 and M 8.131

Description

The lifting module Shop-Floor suitable for lifting and lowering tures, working tables and objects in industrial application for medical treatment equipme applications.

In general, lifting modules are u unit of devices for controlled liftir of loads or for height adjustment



Top and bottom plate:

alum natur alum black

Römheld GmbH · Postfach 1253 · 35317 Laubach, Germany · Tel.: +49(0)6405 / 89-0 · info@roemheld.de · www.roemheld.com

Manual-hydraulic version operation with foot pedal



Description

The stroke movement is obtained by a hydraulic lifting drive with single-lever actuation, with oil being pumped by means of a piston pump into a plunger cylinder.

During retraction the oil returns due to the weight of the load from the cylinder back to the reservoir. A defined speed reduction is effected, independent of the load.

The manual-hydraulic variant is particularly sturdy and durable. This variant meets high safety demands and withstands jerking and knocking loads in applications.

According to the application 3 different force levels can be selected. The number of pump strokes depends on the force level.

Operation

Stroke

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To lift the load, the foot pedal has to be depressed by approx. 40° several times. The pedal returns to its off-position by means of a return spring.

To lower the load, the foot pedal has to be moved upwards by approx. 10°.

Stroke [mm]	A [mm]	A + stroke [mm]	Weight [kg]	
200	420	620	15	
300	520	820	20	
400	620	1,020	25	
500	720	1,220	30	
600	820	1,420	35	
500	720	1,220	30	

Lifting force [N]	Pump strokes per 100 mm	Descent speed [mm/s]
2,000	5	approx. 45
4,000	7	approx. 22
6,000	9	approx. 22

Accessories

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Dimensions

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Detail "X"

 Base plate for increased stability as per data sheet M 8.100

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Important notes

To descend the lifting module a minimum load of approx. 200 N is required.

The lifting module must only be pressure loaded. The centre of gravity should be within the traverse of the fixing screws. If the centre of gravity is outside, the dowelled joint with the floor has to be dimensioned correspondingly. In such cases it is recommended to use a larger base plate.

In case of eccentric load of more than 250 mm, the column cannot descend automatically because of too high friction forces.

The lifting module is designed for applications within closed rooms.

The hydro-manual lifting drive can not be operated with synchronization control.

Code for part numbers

Part no.

8915-0X-X0-H

Maximum lifting force

- 2 = 2.000 N
- 4 = 4.000 N

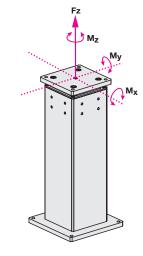
6 = 6,000 N

Stroke -

- 2 = 200 mm
- 3 = 300 mm
- **4** = 400 mm

5 = 500 mm **6** = 600 mm

Maximum lifting force and maximum admissible torque load



Maximum lifting force Fz

Optionally 2,000 N, 4,000 N or 6,000 N (1,000 N only for the electro-mechanical version)

Maximum torque load:

Total M _X /y:	500 Nm
Mz:	300 Nm

In the case of eccentric loads, it is recommended to compensate these by counterweights. In off-position, the indicated maximum torques may occur.

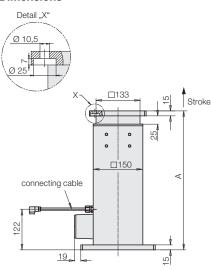
The forces and torgues have to be considered by the operator. During the lifting motion, only 50 % of the maximum values are admitted.

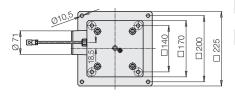
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Electro-mechanical version



Dimensions





Accessories

 Base plate for increased stability as per data sheet M 8.100

Description

The lifting motion is generated by an electric motor with a spindle lifting gear.

The electrically operated variant is particularly suitable for positioning and adjusting tasks of working tables as well as for material supply and transport.

They excel by a smooth running.

Operation

Lifting and lowering with hand panels or foot switches as per data sheet M 8.203 is triggered by touch control. After release of the pushbutton, the motion will be immediately stopped. The hand panel with memory function allows to store 5 positions, which can be approached via corresponding via corresponding position push-buttons.

(for detailed description see data sheet M 8.203)

Synchronization

Up to 4 lifting modules can be operated with synchronization control by a corresponding control module.

For example complete lifting platforms can be designed.

Due to the control modules, variants with 4 or 6 kN lifting force are only suitable for synchronization control with the code letter G.

Variants with 2 kN lifting force can be operated in synchronization control in variants G as well as B and I.

Please also pay attention to the instructions for the operation of lifting modules in synchronism on data sheet M 4.005.

Control units with synchronization control for 2, 3, or 4 lifting modules are available.

Technical data

Electric connection	Plug
Duty cycle	15 % ED
Code class	IP 54
Control voltage	24 V DC

Variant E, I and B

-,	
Lifting speed (load-dependent)	Current consumption (load dependent)
[mm/s]	[A]
3228	7
1816	5
108	6
75	7.5
	Lifting speed (load-dependent) [mm/s] 3228 1816 108

Variant G

Lifting force	Lifting speed (load-dependent)	Current consumption (load dependent)
[N]	[mm/s]	[A]
2,000	1816	5
4,000	86	4.5
6,000	64	5.5

Important notes

Maximum admissible torque load as per manual-hydraulic version (see page 2) . The maximum pull force of the electro-mechanical version is 80% of the push force!

Code for part numbers

8915-0X-X0-X

Maximum lifting force-

- 1 = 1,000 N (only for variant E + B)
- **2** = 2,000 N

Part no.

- **4** = 4,000 N
- **6** = 6,000 N

Stroke

- **2** = 200 mm
- **3** = 300 mm **4** = 400 mm
- 5 = 500 mm
- **6** = 600 mm
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Electronics

- E = integrated stroke end disconnection (not suitable for synchronization control) with smooth connecting cable, 2.5 m
- G = with incremental stroke measuring system (suitable for synchronization control) with smooth connecting cable, 2.5 m
- I = with incremental stroke measuring system (suitable for memory function) with smooth connecting cable, 2.5 m
- **B** = with incremental stroke measuring system (suitable for memory function and battery mode)
 - with smooth connecting cable, 1.0 m

In case of the variant with a lifting force of 2,000 N, the electronic variant ${\bf G}$ is identical with the variant ${\bf I}.$

Delivered will be always variant **G**, which is suitable for memory function as well as for synchronization.

Delivery

The lifting modules are delivered ready for connection. The connecting cable from the lifting module to the control module is included in the delivery. Operating elements as well as control modules and mains cables can be ordered separately as an accessory.

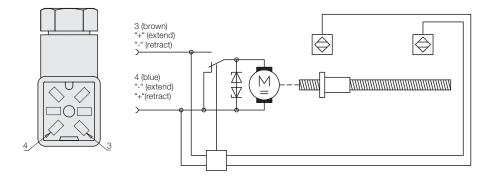
Electrical accessories required for a functional system:

- Control module as per data sheet M 8.200
 or
- Control module with battery holder as per data sheet M 8.201
- Hand panels, foot switch and mains cable as per data sheet M 8.203

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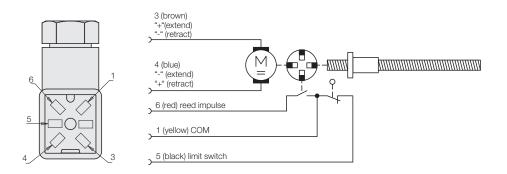
Circuit diagram and connection

plug-type connectors for lifting modules with stroke end disconnection (with last digit E)

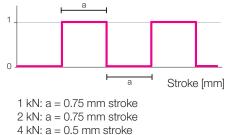


Circuit diagram and connection

plug-type connectors for lifting modules with incremental stroke measuring system (with last digit I, B and G)



Resolution of the incremental stroke measuring system



4 kN: a = 0.5 mm stroke6 kN: a = 0.375 mm stroke

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